

QG series



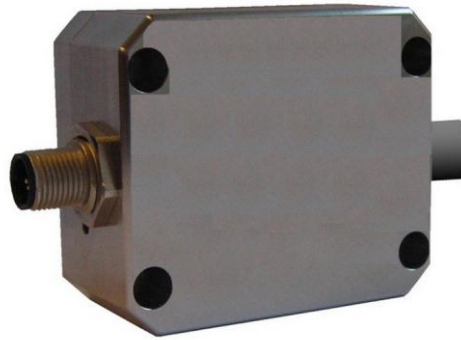
QG76-SD-030H-CAN-CFM

Inclination sensor
2 axis horizontal mounting

Output
CANopen

Supply voltage
10 - 30V dc

Measuring range
 $\pm 30^\circ$



CANopen



QG76-SD-030H-CAN-CFM

Housing
Dimensions
Mounting
Ingress Protection (IEC 60529)
Relative humidity
Weight
Supply voltage
Polarity protection
Current consumption
Operating temperature
Storage temperature
Measuring range
Centering function
Frequency response (-3dB)
Accuracy
Offset error
Non linearity
Sensitivity error
Resolution
Temperature coefficient
Max mechanical shock
CAN interface (hardware)
CAN communication profile
Baud rate
Node Id
TPDO
Event time
Sync mode
Heartbeat
Programming options
Output format
Temperature compensation
Filtering
Modes of operation
Integrated termination resistor
Boot up time

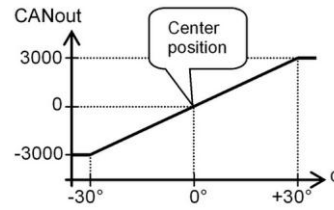
General specifications v20140723

Stainless steel
70x60x33 mm
4x M4x25 mm stainless steel pozidrive screws (optional: 2x Ø4mm positioning pins)
IP67
0 - 100%
ca. 700 gr
10 - 30V dc
Yes
≤ 50 mA
-40 .. +85°C
-40 .. +85°C
$\pm 30^\circ$
Yes (CANout 0 = 0°), range: $\pm 5^\circ$
10 Hz
overall 0,04° typ.
$< \pm 0,03^\circ$ typ. ($< \pm 0,08^\circ$ max.) after centering
$< \pm 0,02^\circ$ typ. ($< \pm 0,07^\circ$ max.)
$< \pm 0,02\%$ typ. ($< \pm 0,07\%$ max.)
0,01°
$\pm 0,005^\circ/K$ typ.
20.000g
CAN 2.0 A and B according to ISO 11898-1 & ISO 11898-2
CANopen, CiA301 V4.2.0 & EN 50325-4
125 kbit/s (default), 250 kbit/s, 500 kbit/s, 1Mbit/s 01h (range: 01h - 7Fh) TPDO1: 181h (for Node ID=01h) TPDO1: 5 - 500 ms (default: 100 ms) On/off (default: off) On/off (default: on, 2s)
Baudrate, Node Id, Event time, Sync mode, Heartbeat, Output format Integer: -3000 to +3000 (PDO1:X=byte2,1;Y=byte4,3) Yes Input filter enabled, output filter disabled Event mode, Sync-mode Optional, default: no
< 1 s

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CANoutput = $100 \cdot \alpha$
clipping outside measuring range

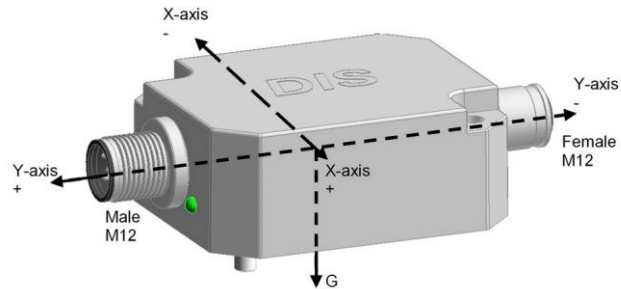
Transfer characteristic



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Default 0°: horizontal, no acceleration applied.
Cross tilt sensitivity error:
 $< (0,12 \cdot \text{cross tilt angle})^2$ % typ.
Note:
one axis $< 10^\circ$ tilt for max. accuracy

Measurement orientation



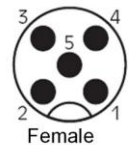
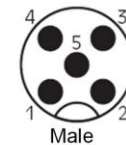
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Connection

Wire / pin coding

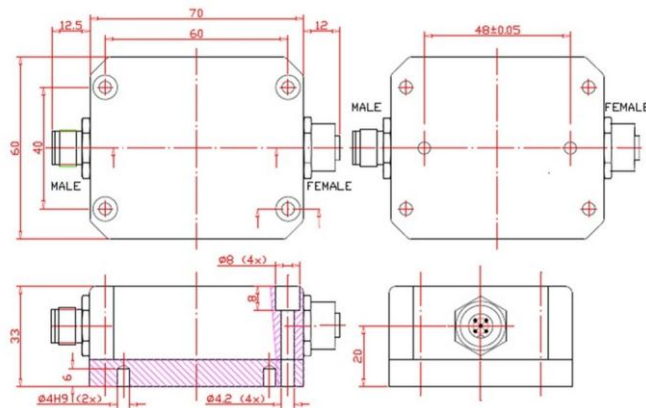
M12 connectors: 1x male + 1x female (5 pins, A-coding) (CiA303 V1.8.0)

Pin 1: Shield
Pin 2: Vcc
Pin 3: Gnd & CAN_GND
Pin 4: CAN_H
Pin 5: CAN_L



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Mechanical dimensions



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Center function, CAN-manual, EDS-file

Centering can be done to eliminate mechanical offsets. (can be done by CAN object 300Fh)
The current sensor position will be stored as the new Center position in the internal Eeprom.

A CAN-manual is available at www.dis-sensors.com, see 'downloads'

EDS-file (CiA306 V1.3.0) is available at www.dis-sensors.com, see 'downloads'